

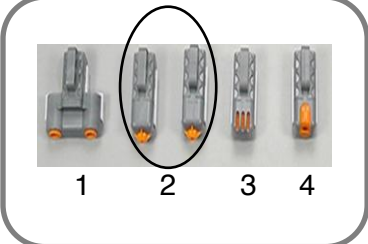
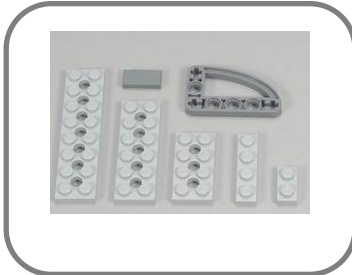

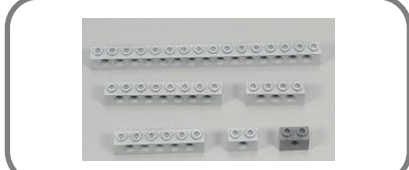
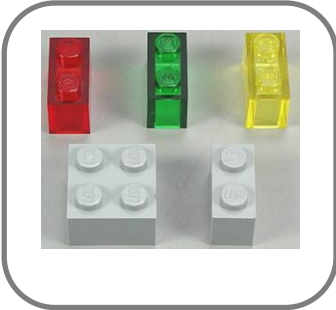

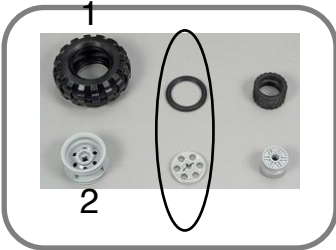




Name _____

Date _____

	CATEGORY NAME	FUNCTION
1.	 <p>NXT MICROPROCESSOR</p>	<p>ALLOWS ROBOT TO SENSE OR REACT TO ITS ENVIRONMENT</p>
2.	 <p>INTERACTIVE SMART MOTOR (ROTATION)</p>	<p>ALLOWS ROBOT TO SENSE OR REACT TO ITS ENVIRONMENT</p>
3.	 <p>SENSORS 1. ULTRASONIC 2. TOUCH 3. SOUND 4. LIGHT</p>	<p>ALLOWS ROBOT TO SENSE OR REACT TO ITS ENVIRONMENT</p>
4.	 <p>PLATES (FLAT STRUCTURES)</p>	<p>PROVIDES STABILITY</p>
5.	 <p>TECHNIC (ODD)</p>	<p>PROVIDES STABILITY</p>
	 <p>STUDED BEAM (EVEN)</p>	

	CATEGORY NAME	FUNCTION
6. 	BRICKS	PROVIDES STABILITY
7. 	GEARS (NAMED BY TOOTH COUNT)	TRANSMITS MECHANICAL ENERGY WITHIN ROBOT
8. 	WHEEL 1. TIRES 2. HUBS (CAN BUILD A PULLEY SYSTEM USING HUB AND RUBBERBAND)	TRANSMITS MECHANICAL ENERGY WITHIN ROBOT
9. 	AXLES (NAMED BY LINING UP TO STUD BEAM AND COUNTING STUDS)	TRANSMITS MECHANICAL ENERGY WITHIN ROBOT
10. 	PEGS FRICTION PEGS (BLUE) NON FRICTION (TAN)	JOIN STRUCTURAL ELEMENTS TOGETHER